









- Automatic system using a collaborative robot and cameras
- The solution based on 3D vision and machine learning for picking, placing and inserting parts
- Utilize for Under-hood fuse box manufacturing process: Perform stable assembly work



NP1 3D Vision based Robot System



Technical Data

ITEM		NP1
ROBOT	DEGREE OF FREEDOM	6
	WORKSPACE	Max. 1700 mm
	REPEATABILITY	± 0.1 mm
	PAYLOAD	Max. 6 kg
	PRESS FORCE	Max. 16 N
GRIPPER	DRIVE	BLDC Motor
	STROKE PER JAW	Max. 80 mm
	NOMINAL GRIPPING FORCE	1800 N
CAMERA	DEPTH TECHNOLOGY	Active IR Stereo
	SENSOR SHUTTER TYPE	Global Shutter
	DEPTH RESOLUTION	Up To 1280 x 720
	RGB RESOLUTION	Up To 1920 x 1080
	FRAME RATE	Up To 90 fps



Headquarters #1313, 184, Gasan digital 2-ro, Geumcheon-gu, Seoul 08501, Republic of Korea

China Branch

No. 1-2, Tianning Road, Caomiaozi Town, Lingang Economic and Technological Development Zone, Weihai, Shandong 264211, China (山东省威海临港经济技术开发区草庙子镇天宁路1-2号)



Vietnam Branch

Lot CN7-3, Yen Phong II-C Industrial Park, Cho Town, Yen Phong District, Bac Ninh Province 16206, Vietnam